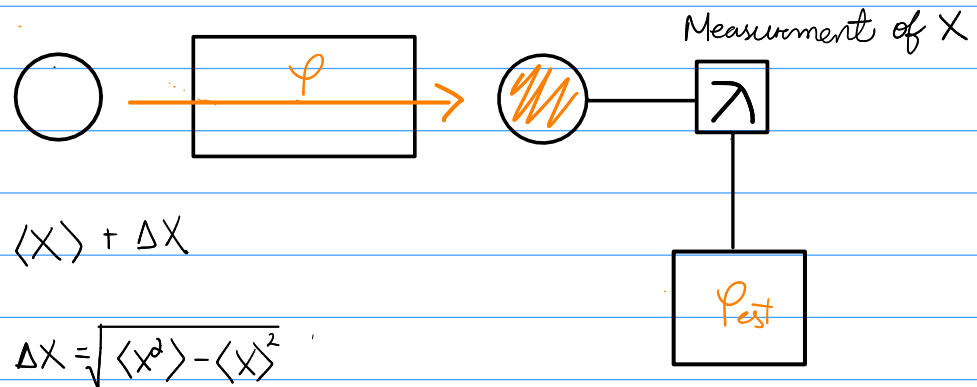


Metrology: measuring a system and learning unknown parameter

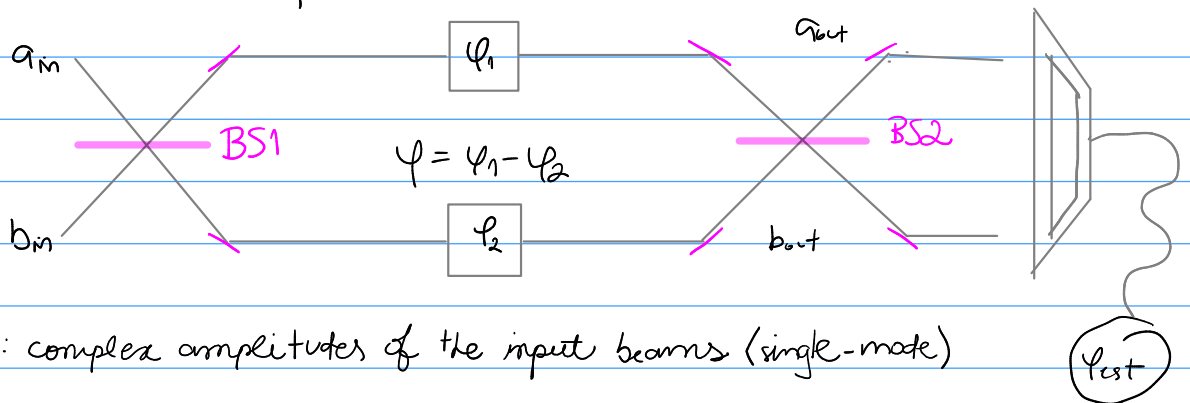


$$\Delta \varphi = \sqrt{\langle P_{est}^2 \rangle - \langle P_{est} \rangle^2} \rightarrow \text{estimation uncertainty}$$

- Uncertainty propagation formula: $\Delta \varphi = \frac{\Delta X}{\left| \frac{d\langle X \rangle}{d\varphi} \right|}$

- OUR FOCUS: Optical interferometry (Progress in Optics 60, 345 (2015))

Mach-Zehnder interferometer:



a, b : complex amplitudes of the input beams (single-mode)

* High phase sensitivity is important in many applications
e.g. LIGO interferometer

* BS1: 50/50; the beams acquire $-\pi/2$ phase

$$\begin{pmatrix} a_{in} \\ b_{in} \end{pmatrix} \Rightarrow \text{BS1: } \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & e^{i\pi/2} \\ e^{i\pi/2} & 1 \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & -i \\ -i & 1 \end{pmatrix}$$

e.g. action of beam splitter on beam a

$$\frac{1}{\sqrt{2}} \begin{pmatrix} 1 & -i \\ -i & 1 \end{pmatrix} \begin{pmatrix} a_{in} \\ 0 \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} a_{in} \\ -i a_{in} \end{pmatrix}$$

- BS2: beams acquire a $\pi/2$ phase

- Total transformation of the input beams

$$\begin{pmatrix} a_{out} \\ b_{out} \end{pmatrix} = \underbrace{\frac{1}{\sqrt{2}} \begin{pmatrix} 1 & i \\ i & 1 \end{pmatrix}}_{BS2} \begin{pmatrix} e^{i\phi_1} & 0 \\ 0 & e^{i\phi_2} \end{pmatrix} \underbrace{\frac{1}{\sqrt{2}} \begin{pmatrix} 1 & -i \\ -i & 1 \end{pmatrix}}_{BS1} \begin{pmatrix} a_{in} \\ b_{in} \end{pmatrix}$$

* Nonclassical features of light: better sensitivity?

• Available light sources: single-photon, coherent and squeezed states.

- To deal with this, we replace the complex field amplitude \hat{a} with the operator \hat{a} :

$$\begin{array}{ll} a \rightarrow \hat{a} & a^* \rightarrow \hat{a}^\dagger \\ b \rightarrow \hat{b} & b^* \rightarrow \hat{b}^\dagger \end{array} \quad [\hat{a}, \hat{a}^\dagger] = 1$$

- A single-mode can contain a large number of photons (photons are bosons)

→ state with definite number of photons: $|N\rangle$,

$$\begin{cases} \hat{a}|N\rangle = \sqrt{N}|N-1\rangle \leftarrow \\ \hat{a}^\dagger|N\rangle = \sqrt{N+1}|N+1\rangle \leftarrow \end{cases}$$

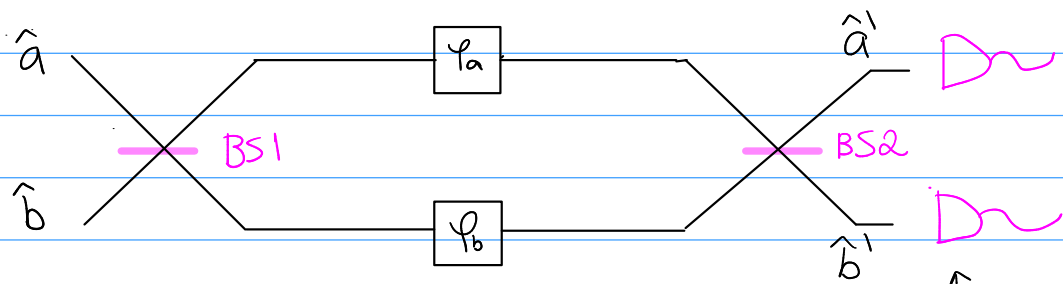
→ $\hat{a}^\dagger \hat{a}|N\rangle = N|N\rangle \rightarrow \hat{N} = \hat{a}^\dagger \hat{a} \rightarrow$ Hermitian

→ $\{|N\rangle\}_N \rightarrow$ Fock basis

→ Pure state $|\psi\rangle = \sum_N c_N |N\rangle$

→ Born rule: $P(N) = |\langle N|\psi\rangle|^2 = |c_N|^2$

... Back to the MZ interferometer:



$$\varphi = \varphi_a - \varphi_b, \quad \hat{n} = \hat{a}^\dagger \hat{a} - \hat{b}^\dagger \hat{b}$$

↑
number of photons

$$\begin{aligned} \begin{pmatrix} \hat{a}' \\ \hat{b}' \end{pmatrix} &= \frac{1}{2} \begin{pmatrix} 1 & i \\ i & 1 \end{pmatrix} \begin{pmatrix} e^{i\varphi_a} & 0 \\ 0 & e^{i\varphi_b} \end{pmatrix} \begin{pmatrix} 1 & -i \\ -i & 1 \end{pmatrix} \begin{pmatrix} \hat{a} \\ \hat{b} \end{pmatrix} \\ &= e^{i(\varphi_a + \varphi_b)} \begin{pmatrix} \cos(\varphi/2) & -\sin(\varphi/2) \\ \sin(\varphi/2) & \cos(\varphi/2) \end{pmatrix} \begin{pmatrix} \hat{a} \\ \hat{b} \end{pmatrix} \end{aligned}$$

- Jordan-Schwinger transformation (Yurke et al., 1986)

$$\hat{J}_x = \frac{1}{2} (\hat{a}^\dagger \hat{b} + \hat{b}^\dagger \hat{a})$$

$$\hat{J}_y = \frac{i}{2} (\hat{b}^\dagger \hat{a} - \hat{a}^\dagger \hat{b}) \quad \Rightarrow \quad [\hat{J}_x, \hat{J}_y] = i \hat{J}_z$$

$$\hat{J}_z = \frac{1}{2} (\hat{a}^\dagger \hat{a} - \hat{b}^\dagger \hat{b}) = \frac{1}{2} \hat{n}$$

$$\text{Total angular momentum } \hat{J} = \frac{\hat{N}}{2} (\hat{N} + 1), \quad \hat{N} = \hat{a}^\dagger \hat{a} + \hat{b}^\dagger \hat{b}$$

→ Action of elements

$$\hat{a}' = U \hat{a} U^\dagger, \quad \hat{b}' = U \hat{b} U^\dagger, \quad U = \exp(-i \alpha \hat{J} \cdot \hat{s})$$

→ Balanced beam splitter: $U = e^{-i \pi/2 \hat{J}_x}$

→ Phase delay: $U = e^{-i \varphi \hat{J}_z}$

We can now write

$$\begin{pmatrix} \hat{J}_x' \\ \hat{J}_y' \\ \hat{J}_z' \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & -1 & 0 \end{pmatrix} \begin{pmatrix} \cos\varphi & -\sin\varphi & 0 \\ \sin\varphi & \cos\varphi & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} \hat{J}_x \\ \hat{J}_y \\ \hat{J}_z \end{pmatrix}$$

rotation x-axis
rotation y-axis
rotation z

$$= \begin{pmatrix} \cos\varphi & 0 & \sin\varphi \\ 0 & 1 & 0 \\ -\sin\varphi & 0 & \cos\varphi \end{pmatrix} \begin{pmatrix} \hat{J}_x \\ \hat{J}_y \\ \hat{J}_z \end{pmatrix}$$

Therefore, we get

$$\hat{J}_x' = \cos\varphi \hat{J}_x + \sin\varphi \hat{J}_z$$

$$\hat{J}_y' = \hat{J}_y$$

$$\hat{J}_z' = \cos\varphi \hat{J}_z - \sin\varphi \hat{J}_x$$

no Heisenberg picture.

Note that

$$|\psi\rangle_{\text{out}} = \exp(-i\pi/2 \hat{J}_x) \exp(-i\varphi \hat{J}_z) \exp(i\pi/2 \hat{J}_x) |\psi\rangle_{\text{in}}$$

From the Heisenberg picture,

$$\langle \hat{J}_z \rangle_{\text{out}} = \cos\varphi \langle \hat{J}_z \rangle_{\text{in}} - \sin\varphi \langle \hat{J}_x \rangle_{\text{in}}$$

and the variance reads

$$\Delta^2 \hat{J}_z |_{\text{out}} = \cos^2\varphi \Delta^2 \hat{J}_z |_{\text{in}} + \sin^2\varphi \Delta^2 \hat{J}_x |_{\text{in}} - 2 \sin\varphi \cos\varphi \text{cov}(\hat{J}_x, \hat{J}_z) |_{\text{in}}$$

$$\text{where } \text{cov}(\hat{J}_x, \hat{J}_z) = \frac{1}{2} \langle \hat{J}_x \hat{J}_z + \hat{J}_z \hat{J}_x \rangle - \langle \hat{J}_x \rangle \langle \hat{J}_z \rangle$$

- Precision of estimation $\Delta\varphi$:

$$\Delta\varphi = \frac{\Delta \hat{J}_z |_{\text{out}}}{\left| \frac{d\langle \hat{J}_z \rangle_{\text{out}}}{d\varphi} \right|}$$

A) Fock state interferometry

$$\boxed{|\psi\rangle_{in} = \underline{|N\rangle}_a \underline{|0\rangle}_b}$$

$$\Rightarrow \hat{J}_z |N\rangle_a |0\rangle_b = \frac{1}{2} (\hat{a}^\dagger \hat{a} - \hat{b}^\dagger \hat{b}) |N\rangle_a |0\rangle_b = \frac{1}{2} N |N\rangle_a |0\rangle_b$$

$$\Delta^2 \hat{J}_z |in\rangle = 0$$

$$\langle \hat{J}_z \rangle_{in} = \langle N, 0 | \hat{J}_z | N, 0 \rangle = \frac{1}{2} N$$

$$\langle \hat{J}_x \rangle_{in} = \frac{1}{2} \langle N, 0 | \hat{a}^\dagger \hat{b} + \hat{b}^\dagger \hat{a} | N, 0 \rangle = 0 \quad \begin{aligned} \langle 0 | \hat{b} | 0 \rangle &= 0 \\ \hat{b} | 0 \rangle &= 0 \end{aligned}$$

$$\Delta^2 J_x |in\rangle = \langle \hat{J}_x^2 \rangle_{in} - \langle \hat{J}_x \rangle_{in}^2$$

$$\hat{J}_x^2 = \frac{1}{4} (\hat{a}^\dagger \hat{a} \hat{b} \hat{b}^\dagger + \hat{a}^\dagger \hat{a}^\dagger \hat{b} \hat{b} + \hat{a} \hat{a}^\dagger \hat{b}^\dagger \hat{b} + \hat{a} \hat{a} \hat{b}^\dagger \hat{b}^\dagger)$$

$$\langle \hat{J}_x^2 \rangle_{in} = \frac{1}{4} N$$

$$\Delta^2 J_z |out\rangle = \frac{1}{4} N \sin^2 \varphi$$

$$\langle \hat{J}_z \rangle_{out} = \frac{1}{2} N \cos \varphi$$

$$\rightarrow \Delta \varphi = \frac{\Delta \hat{J}_z |out\rangle}{\left| \frac{d \langle \hat{J}_z \rangle_{out}}{d \varphi} \right|} = \frac{\frac{1}{2} \sqrt{N} |\sin \varphi|}{N |\cancel{\sin \varphi}| \frac{1}{2}} = \frac{1}{\sqrt{N}}$$

↑
shot-noise limit.

B) Coherent states

$$|N_{in}\rangle = |\alpha\rangle_a |0\rangle_b$$

$$\rightarrow \hat{a}|\alpha\rangle = \alpha|\alpha\rangle, \text{ and thus } \langle\alpha|\hat{a}^\dagger = \alpha^*\langle\alpha|, \quad \alpha = |\alpha|e^{i\theta}$$

$$\rightarrow \text{average number of photons: } \langle\alpha|\hat{N}|\alpha\rangle = \alpha^*\alpha = |\alpha|^2$$

→ Fock basis

$$|\alpha\rangle = e^{-|\alpha|^2/2} \sum_{n=0}^{\infty} \frac{\alpha^n}{\sqrt{n!}} |n\rangle$$

$$P(n) = |\langle n|\alpha\rangle|^2 = e^{-|\alpha|^2} \frac{|\alpha|^{2n}}{n!} \leftarrow \text{Poisson dist.}$$

$$\rightarrow \hat{q}_0 = \frac{1}{\sqrt{2}} (\hat{a}e^{-i\theta} + \hat{a}^\dagger e^{i\theta}), \quad \hat{p}_0 = q_0 + \frac{p_0}{2} = \frac{-i}{\sqrt{2}} (\hat{a}e^{-i\theta} - \hat{a}^\dagger e^{i\theta})$$

$$[\hat{q}_0, \hat{p}_0] = i \Rightarrow \Delta p_0 \cdot \Delta q_0 \geq \frac{1}{2}$$

→ in a coherent state $|\alpha\rangle$

$$\Delta p_0 \cdot \Delta q_0 = \frac{1}{2}$$

$$\rightarrow \langle \hat{J}_z \rangle_{in} = \frac{1}{2} \langle \alpha, 0 | \hat{a}^\dagger \hat{a} - \hat{b}^\dagger \hat{b} | \alpha, 0 \rangle = \frac{1}{2} |\alpha|^2$$

$$\rightarrow \langle \hat{J}_x \rangle_{in} = 0$$

$$\rightarrow \Delta^2 \hat{J}_z |_{in} = \Delta^2 \hat{J}_x |_{in} = \frac{1}{4} |\alpha|^2$$

$$\Delta p |\alpha\rangle_a |0\rangle_b = \frac{\Delta \hat{J}_z |_{out}}{\left| \frac{d\langle \hat{J}_z \rangle_{out}}{d\varphi} \right|} = \frac{\frac{1}{2} |\alpha|}{\frac{1}{2} |\alpha| \sqrt{\sin^2 \varphi}} = \frac{1}{|\alpha| \sin \varphi} = \frac{1}{\sqrt{\langle \hat{N} \rangle} \sin \varphi} = \frac{1}{\sqrt{\langle \hat{N} \rangle}}$$

- optimal operating points $\varphi = \frac{\pi}{2}, \frac{3\pi}{2}, \dots$